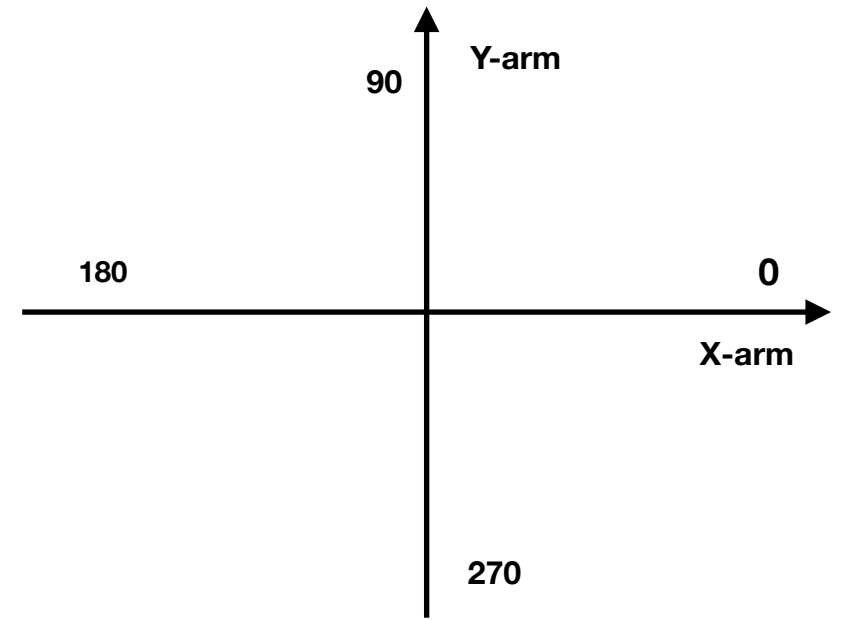
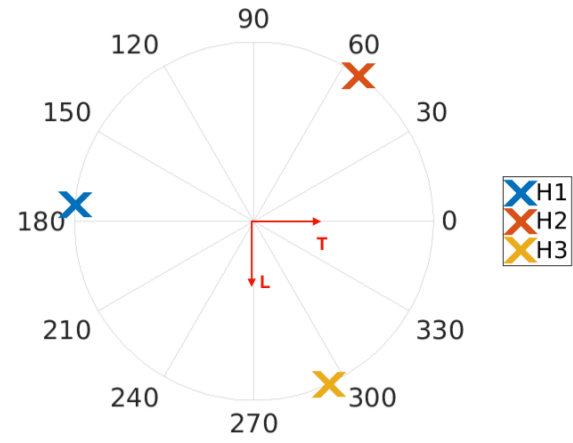
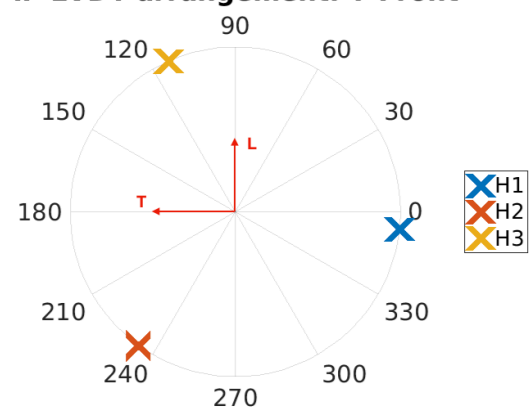


Y-arm

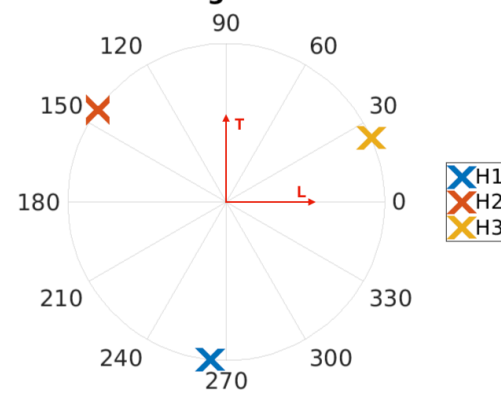
IP LVDT arrangement: Y-End



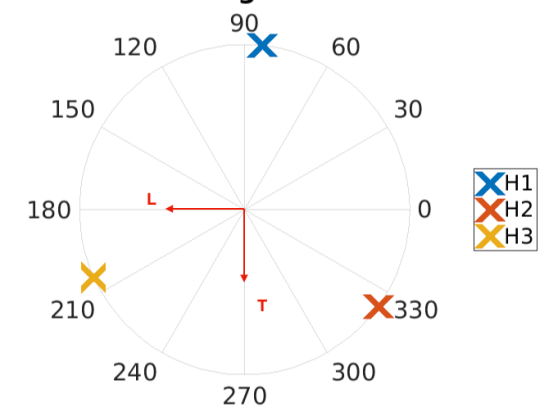
IP LVDT arrangement: Y-Front



IP LVDT arrangement: X-Front

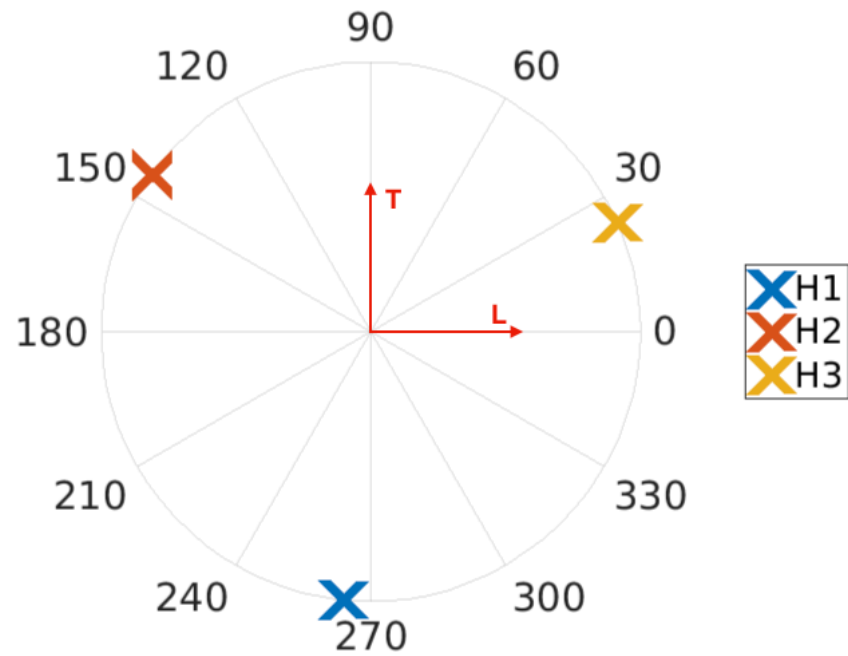


IP LVDT arrangement: X-End



X-arm

IP LVDT arrangement: X-Front



ITMX:geometrical sensing matrix

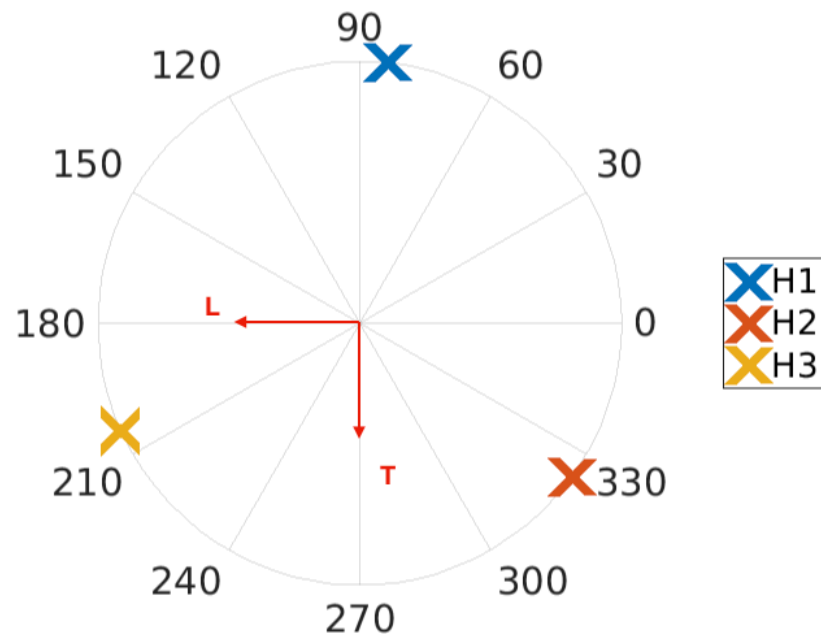
$$\begin{pmatrix} L \\ T \\ Y \end{pmatrix} = \begin{pmatrix} -\sin(\alpha_1) & \cos(\alpha_1) & R \\ -\sin(\alpha_2) & \cos(\alpha_2) & R \\ -\sin(\alpha_3) & \cos(\alpha_3) & R \end{pmatrix}^{-1} \cdot \begin{pmatrix} H_1 \\ H_2 \\ H_3 \end{pmatrix}$$

$$\alpha_1 = 264$$

$$\alpha_2 = 144$$

$$\alpha_3 = 24 \quad R = 0.5940m$$

IP LVDT arrangement: X-End



ETMX:geometrical sensing matrix

$$\begin{pmatrix} L \\ T \\ Y \end{pmatrix} = \begin{pmatrix} \sin(\alpha_1) & -\cos(\alpha_1) & R \\ \sin(\alpha_2) & -\cos(\alpha_2) & R \\ \sin(\alpha_3) & -\cos(\alpha_3) & R \end{pmatrix}^{-1} \cdot \begin{pmatrix} H_1 \\ H_2 \\ H_3 \end{pmatrix}$$

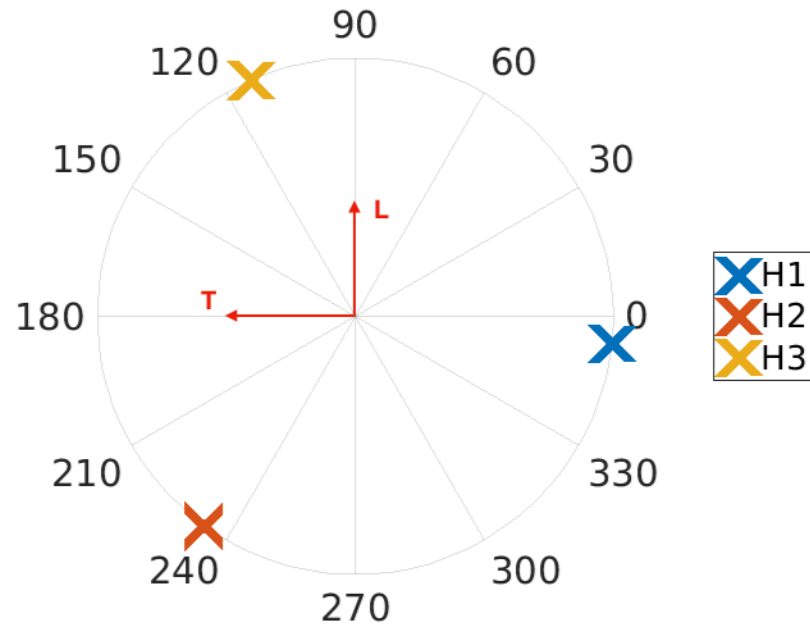
$$\alpha_1 = 84$$

$$\alpha_2 = 324$$

$$\alpha_3 = 204 \quad R = 0.5940m$$

ITMY:geometrical sensing matrix

IP LVDT arrangement: Y-Front



$$\begin{pmatrix} L \\ T \\ Y \end{pmatrix} = \begin{pmatrix} \cos(\alpha_1) & \sin(\alpha_1) & R \\ \cos(\alpha_2) & \sin(\alpha_2) & R \\ \cos(\alpha_3) & \sin(\alpha_3) & R \end{pmatrix}^{-1} \cdot \begin{pmatrix} H_1 \\ H_2 \\ H_3 \end{pmatrix}$$

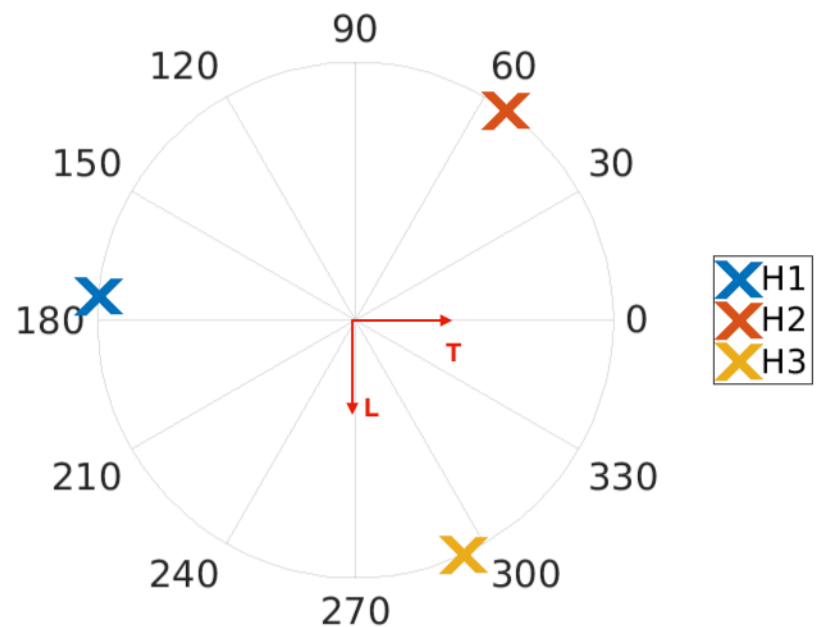
$$\alpha_1 = 354$$

$$\alpha_2 = 234$$

$$\alpha_3 = 114 \quad R = 0.5940m$$

ETMY:geometrical sensing matrix

IP LVDT arrangement: Y-End



$$\begin{pmatrix} L \\ T \\ Y \end{pmatrix} = \begin{pmatrix} -\cos(\alpha_1) & -\sin(\alpha_1) & R \\ -\cos(\alpha_2) & -\sin(\alpha_2) & R \\ -\cos(\alpha_3) & -\sin(\alpha_3) & R \end{pmatrix}^{-1} \cdot \begin{pmatrix} H_1 \\ H_2 \\ H_3 \end{pmatrix}$$

$$\alpha_1 = 174$$

$$\alpha_2 = 54$$

$$\alpha_3 = 294 \quad R = 0.5940m$$